

**AMENDMENTS TO THE CLAIMS**

This listing of claims will replace all prior versions and listings of claims in the application.

**LISTING OF CLAIMS**

1. (currently amended) A pumping system comprising: a pumping mechanism; a motor for driving the pumping mechanism; a drive control for controlling the motor; and means for monitoring at least one state within the system; and wherein, ~~to improve the performance of the system, the drive control is adapted to~~ causes the system to operate for transient periods in an overload condition ~~which can result in said monitored state exceeding a predetermined operational limit, and when operating in said overload condition said drive control and to~~ controls the power to the motor ~~when the system is operating in said overload condition~~ dependent on the level of said monitored state so as to thereby avoiding said state from exceeding said operational limit.
2. (currently amended) ~~A~~The system according to ~~Claim 1~~, wherein the performance is improved by said drive control increasing the power supplied to the motor to a level which can result in said monitored state exceeding a predetermined operational limit.
3. (currently amended) ~~A~~The system according to ~~Claim 1 or Claim 2~~, wherein the drive control causes the system to operate in an overload condition when a load on the motor requires increased power supply to the motor.
4. (currently amended) ~~A~~The system according to ~~any preceding claim 1~~, wherein the drive control does not limit said power unless said state exceeds a predetermined lower limit.

5. (currently amended) A-The system according to ~~Claim 4~~, wherein above said predetermined lower limit, said drive control gradually ~~varies reduces or increases~~ power dependent on said monitored state.
6. (currently amended) A-The system according to ~~any preceding claim 1~~, wherein said drive control includes gain circuitry which can adopt: a gain of 1 thereby not limiting motor power; a gain of zero thereby limiting motor power to zero; and any gain between one and zero, said gain circuitry controlling said gain according to a predetermined relationship with said state.
7. (currently amended) A-The system according to ~~any preceding claim 1~~, wherein the drive control controls the power of the motor by limiting the current supplied to the motor by adjusting ~~the frequency of the voltage and/or the amplitude of the voltage supplied to the motor~~.
8. (currently amended) A-The system according to ~~Claim 7~~, wherein the drive control comprises programmable means for setting a maximum allowable current in said motor ~~thereby so as to~~ setting the extent to which the system can be overloaded.
9. (currently amended) A-The system according to ~~any preceding claim 1~~, wherein said state is a temperature within the system.
10. (currently amended) A-The system according to ~~any preceding claim 1~~, wherein said state is a ~~functional~~ calculation of the thermal load of the motor or drive or ~~any part of~~ the pumping mechanism.
11. (currently amended) A-The system according to ~~Claim 10~~, wherein the drive control estimates the motor thermal load according to:

$$\left( \frac{I_{Motor}}{I_{Rated}} \right)^2 \times \frac{1}{1 + s\tau}$$

where:

$I_{motor}$  is the current in the motor;

$I_{rated}$  is a rated current above which said motor is operating in said overload condition;

$\tau$  is a time constant; and

$s$  is the Laplace operator.

12. (currently amended) A-The system according to any of Claims claim 1 to 8, wherein said monitored state within the system is selected from the group of parameters comprising any one or more of a pressure, a current, a voltage, an impedance, or a temperature.
13. (currently amended) A-The system according to any preceding claim 1, wherein the drive control comprises means for receiving input from one or more a sensors for monitoring one or more said the at least one states within the system, and when the drive control causes the system to operate for transient periods in an overload condition the power to the motor is controlled to avoid said one or more the at least one states from exceeding the predetermined operational limit.
14. (currently amended) A-The system according to Claim 13, wherein the one or more sensors are is for sensing a parameter selected from the group comprising one or more of gas pressure, temperature, voltage, or impedance within the system.
15. (currently amended) A-The system according to any preceding claim 1, wherein the drive control comprises a variable speed drive for controlling the power to the motor dependent on the level of said monitored state thereby avoiding said state from exceeding said operational limit.
16. (currently amended) A-The system according to any preceding claim 1, wherein the drive control comprises analogue means for controlling the power

to the motor dependent on the level of said monitored state thereby avoiding said state from exceeding said operational limit.

17. (currently amended) ~~A-The~~ system according to ~~any preceding claim 1,~~ wherein the drive control is operable to prevent said system from operating in an overload condition.
18. (currently amended) ~~A-The~~ system according to ~~any preceding claim 1,~~ wherein said pumping mechanism is a vacuum pumping mechanism.
19. (original) A method of controlling a pumping system comprising: a pumping mechanism; a motor for driving the pumping mechanism; and a drive control for controlling the power to the motor, wherein said method comprises improving the performance of the system by causing the system to operate for transient periods in an overload condition which can cause said monitored state to exceed a predetermined operational limit, and, when operating in said overload condition, controlling the power to the motor dependent on the level of said monitored state thereby avoiding said state from exceeding said operational limit.